Sundar Sripada Venugopalaswamy Sriraman

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F1 - OPT (authorized to work in the US, sponsorship not required)

Machine Learning Engineer | AI Engineer

Experience

Research Engineer Jan 2025 – Present Al Safety Camp Remote	
 AI Safety Camp Conducting empirical research on adversarial behaviors in LLMs trained with PPO and DRRN policies, with the goal of developing 	
representations to classify and counteract adversarial reward optimization strategies	,
Software Engineer Intern Jun 2023 – Aug 2023	,
Hewlett Packard Enterprise San Jose, CA	
• Enhanced scale characterization of Aruba's network management tool by developing Virtual Machine (VM) simulation support in	
Python, doubling the tool's device handling capacity by up to 2,000,000 simulated devices	
• Developed CLI-based VM simulation functionality that enables users to simulate VMs within Docker containers deployed with	
Kubernetes, achieving fast on-boarding (<1 minute per VM) to enhance scalability	
• Collaborated in a cross-functional team writing SQL code for extracting VM system information, integrating it into the simulation	
framework to enable scale simulation and support data-driven decisions for cloud infrastructure	
Graduate Research Assistant Aug 2022 – May 2023	;
The University of Texas at Austin Austin	
• Built TensorFlow-based activity recognition model with 87% classification accuracy across 4 tool-use behaviors, enhancing	
ergonomic study of user-tool interaction Pape	<u>er</u>
• Led a team of 3 students in a data collection project using a 9-DOF IMU on a robot arm that emulates human performance	
• Engineered a data processing pipeline with Pandas to analyze a dataset of over 10,000 entries for activity classification	
• Implemented an ML pipeline in TensorFlow Lite (TFLite) and MLFlow for logging utilizing convolutional neural networks (CNN) for	-
real-time edge inference on a Raspberry Pi, achieving 162 ms per prediction for activity classification	
Research Software Engineer Oct 2020 – Jul 2022)
The International Institute of Information Technology Hyderabad, India	1
Designed classification and regression models in scikit-learn to predict the presence and magnitude of drift in self-driving	
vehicles, achieving prediction accuracy of up to 92% with PyTorch	
Automated end-to-end LIDAR data transformation for 100k+ data points of environments in autonomous systems using custom	
Python APIs, cutting model training prep time by 70%	
• Enabled seamless integration with PyTorch DataLoader, accelerating training cycles and reducing human preprocessing errors by over 90%	
• Collaborated with a cross-functional team to implement a model-predictive controller exploiting just-in-time compilation in JAX	
to generate 1000 navigational trajectories per second Pape	<u>er</u>
• Built a custom triplet loss function to train a multi-modal Convolutional Neural Network (CNN) in PyTorch, effectively minimizing	
drift in autonomous driving and improving performance by up to 76.76% over previous SOTA	<u>er</u>
Dublications	

Publications

- New, R, Salazar, CD, Bendaña, J, Sripada V. S., S, Chinchali, S, Fleischmann, KR, & Longoria, RG. "Design, Development, and Testing of a Smart Hand Tool: Achieving Work Task Recognition Using Synthetic Data and Edge Intelligence." Proceedings of the ASME 2024 International Design Engineering Technical Conferences and Computers and Information in Engineering Conference. Volume 2A: 44th Computers and Information in Engineering Conference (CIE). Washington, DC, USA. August 25–28, 2024. V02AT02A026. ASME. <u>https://doi.org/10.1115/DETC2024-142360</u>
- 2. Shrestha, Sloke, Sundar Sripada V. S., Asvin Venkataramanan. "Style Transfer to Calvin and Hobbes comics using Stable Diffusion." arXiv:2312.03993, 2023.

- M. Omama, S. V. S. Sundar, S. Chinchali, A. K. Singh and K. M. Krishna, "Drift Reduced Navigation with Deep Explainable Features," 2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Kyoto, Japan, 2022, pp. 6316-6323, doi: 10.1109/IROS47612.2022.9981330.
- 4. M. Omama, S. S. V. S., S. Chinchali and K. M. Krishna, "LADFN: Learning Actions for Drift-Free Navigation in Highly Dynamic Scenes," 2022 American Control Conference (ACC), Atlanta, GA, USA, 2022, pp. 1200-1207, doi: <u>10.23919/ACC53348.2022.9867473</u>.

Projects

Exposing Gaps in Multilingual LLM Datasets and Benchmarks

AI Safety Fundamentals

 Researched mistranslation challenges in Multilingual LLMs, analyzing impacts on training, inference, benchmarking, and AI safety through dataset biases and evaluation gaps.

Style Transfer with Stable Diffusion on Calvin and Hobbes Comics

ECE 371Q Digital Image Processing - Ram's Horn Best Project Award

• Fine-tuned Stable Diffusion (GAN) on 11,000+ custom comic images over 30,000 training steps, producing high-fidelity style transfer on Calvin and Hobbes comics, winning the Ram's Horn Best Project Award (top 1 of 40+ entries)

Skills

Software Development | Data Processing Pipelines | TensorFlow & PyTorch Modeling | ML Inference Deployment | LIDAR Data Transformation | Autonomous Navigation | Adversarial Reward Optimization | Parallel Programming | Reinforcement Learning | Multilingual LLM Evaluation | Data Collection & Automation

Programming Languages	Python C C++ R MySQL Java Bash MATLAB HTML CSS
Machine Learning	PyTorch TensorFlow TensorFlow Lite XGBoost LangChain PineCone
Data Engineering	pandas numpy ETL Pipelines Apache Spark Apache AirFlow MLFlow Weights & Biases
Systems & Cloud Computing	Docker Kubernetes Raspberry Pi Linux Real-Time Inference Google Cloud Platform (GCP) AWS S3
	EC2 Lambda Glue
Tools	Git CI/CD Jira

Education

The University of Texas at Austin

Master of Science in Engineering (MS), Electrical and Computer Engineering

Relevant Coursework: Algorithms | Applied Machine Learning | Advanced Computer Vision | AI Safety | Parallel Programming | Convex Optimization | Software Architectures

Anna University

Bachelor of Engineering, Electronics and Communication Engineering Relevant Coursework: Data Structures | Linear Algebra | Digital Signal Processing | Deep Learning | Computer Architecture Nov 2023

Feb 2025

<u>Project Link</u>

Paper, Video

Dec 2024

Sept 2020